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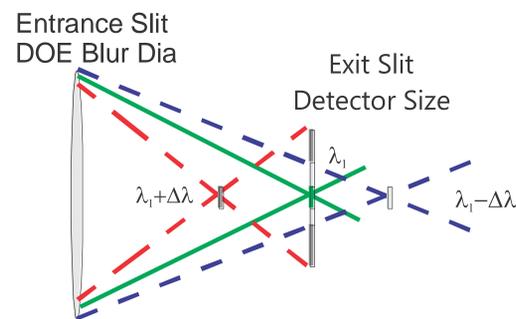
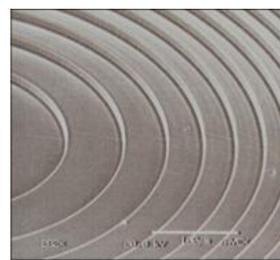


## Objective

- Goal is to demonstrate an extremely small hyperspectral imaging technology that can be configured for different applications; mini-UAV platforms, ground-based robotic vehicles, man carried and fixed position mounted
- This program is a “proof of concept” development effort for a mini-hyperspectral imaging system for standoff detection of respiratory threats, (gas phase chemical warfare agents and TICs)
- The proof of concept will demonstrate the detection of gases and aerosols from an elevated position such as the roof of a building and detect the threat at a slant range of 1 to 5 km with tracking capability for 15 minutes
- Real-time infrared video will be displayed on a computer monitor showing the gas as it is tracked over time
- Proof of concept system will be field tested at the Navy Surface Weapons Center Dahlgren facility

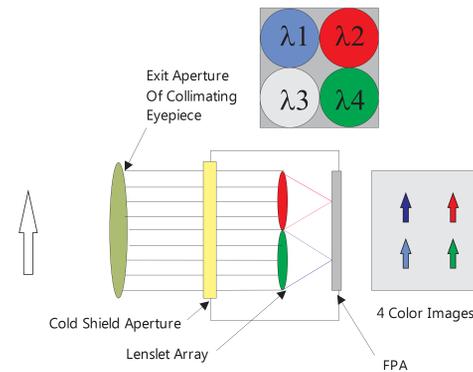
## Foundation of Technology

Diffractive optics have 7 times the chromatic aberrations as compared to conventional optics. This technology exploits this for applications in hyperspectral imaging. In doing so, a system only requires a single optical element to image and disperse the light into its spectral information.



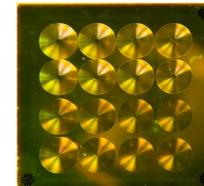
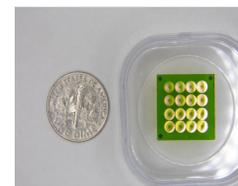
## Simultaneous Multispectral Imaging

Using MOEMS photolithographic processing the diffractive optical elements can be made in an array of lenses where each lens is tuned with a different blaze for a unique wavelength. Then using division of aperture multiple different color images of the scene can be imaged in each frame of the camera.



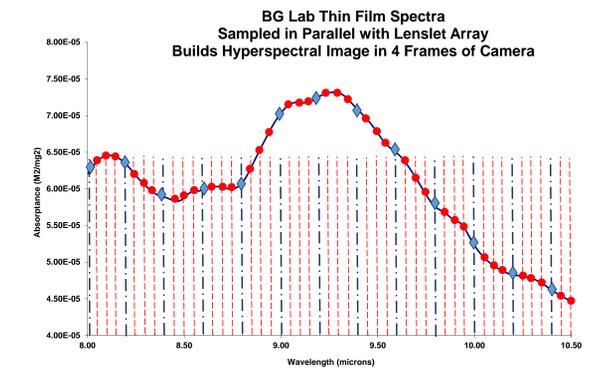
## Lenslet Array Spans SWIR & MWIR

Shown here is the lenslet array that is about the size of a dime. Each lenslet is blazed with a different wavelength from 1.5 to 4.0 microns and is mounted in a baffled holder that sits 7 mm above the Focal Plane Array.



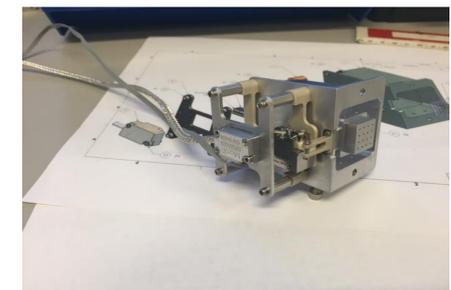
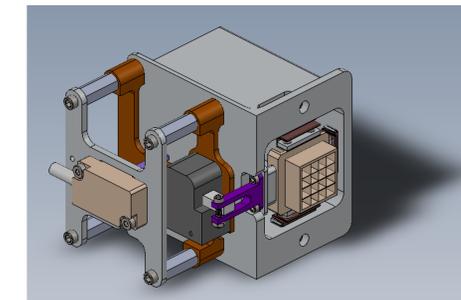
## Multispectral to Hyperspectral

Shown in this graph and indicated by the blue triangles are 16 different blazed spectral lenses in the 4 x 4 lenslet array. By translating the lenslet along the focal length the wavelength between the blue diamond can be imaged in subsequent frames. In less than a second an entire hyperspectral image data cube can be collected.



## Lenslet Array Actuation System

Actuation system consists of piezo electric motor driver with optical encoder. Lenslet array holder is cooled and isolated from the actuation system.





# Title

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